

FIG. 2

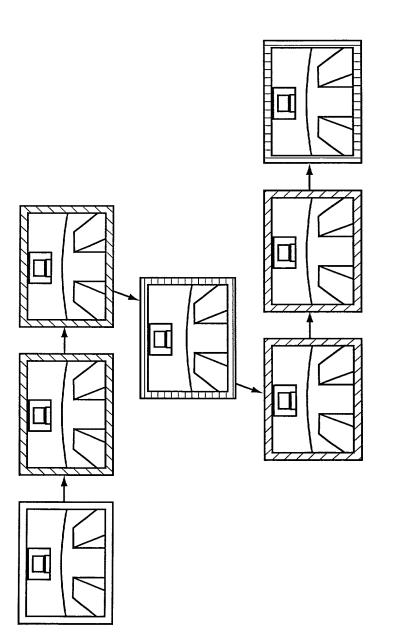


FIG. 3

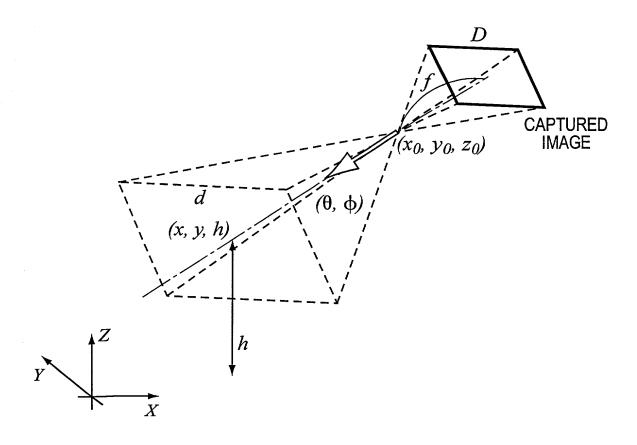
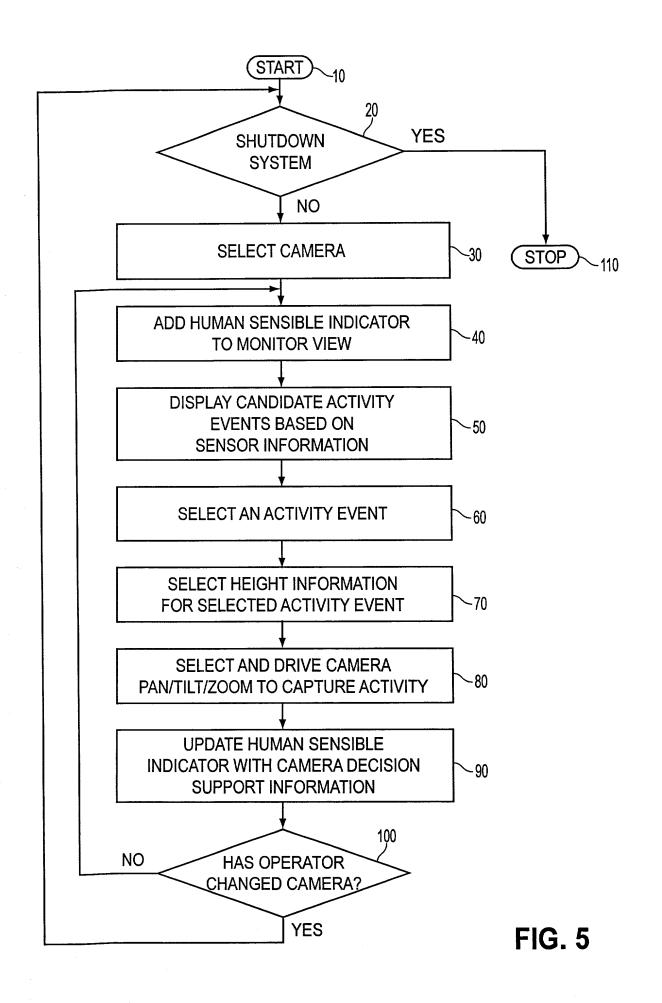


FIG. 4



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08	ACTION	AUTOTRACKING	30	20	45	5	
07 /	OBJECT	CAMERA	CAMERA HOLD MAX	CAMERA HOLD MIN	CAMERA HOLD MAX	CAMERA HOLD MAX	
09	MEETING TYPE	TOWN MEETING	TOWN MEETING	TOWN MEETING	TELECONFERENCE	TELECONFERENCE	

F.G. 6

if(target1.location) == near(front_of_table) then target1.height=SITTING;	if(target1.location) == far(front of table) then target1.height=STANDING;	if(target1.location) == near(front of podium) then (active_camera = camer3, target1.height=15);	ifif(harnet1 location) == near(back of table) then target1.height=STANDING;	ns ns

FIG. 7